Student's report

Numerical methods in theory of topological soliton

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Abstract

In this project we consider kink (antikink) solutions for three model of field: ϕ^4 , ϕ^6 and Sine Gordon. We use numerical methods to find static solutions and moving kink solution for ϕ^4 theory.

1 First view

Follow the Wikipedia a **soliton** or **solitary wave** is a self-reinforcing wave packet that maintains its shape while it propagates at a constant velocity. This waves are ubiquitous in nature and have many applications in nonlinear dynamics.

2 General theory

The most elementary topological solitons arise in 1+1 dimensional space that involve a single scalar field. An general Lagrangian of such scalar field can be written as,

$$L = \frac{1}{2} \partial_{\mu} \phi \partial^{\mu} \phi - U \tag{1}$$

which lead to the corresponding field equation

$$\partial_{\mu}\partial^{\mu}\phi + U' = 0 \tag{2}$$

in Minkovsky signature

$$\partial_{tt}^2 \phi - \partial_{xx}^2 \phi + U' = 0 \tag{3}$$

for the static solution we consider

$$\partial_{xx}^2 \phi - U' = 0 \tag{4}$$

with boundary conditions corresponding vacua

$$\phi(-\infty) = \pm 1, \ \phi(+\infty) = \mp 1 \tag{5}$$

3 ϕ^4 model

$$U = \frac{1}{2}(1 - \phi^2)^2 \tag{6}$$

this model has two vacua

$$\phi(-\infty) = \pm 1, \ \phi(+\infty) = \mp 1 \tag{7}$$

for kink solution we give

$$\phi(-\infty) = -1, \ \phi(+\infty) = 1$$
 (8)

solution is

$$\phi = \tanh(x - x_0) \tag{9}$$

but we found it numerically, using Newton method



For moving kink analitical solution we make some calculus

$$\phi_{tt} - \phi_{xx} + 2\phi(\phi^2 - 1) = 0 \tag{10}$$

$$\phi(x,t) = \phi(x - vt) = \phi(z) \tag{11}$$

$$(v^2 - 1)\phi'' + 2\phi(\phi^2 - 1) = 0| \cdot \phi'$$
(12)

$$(v^{2} - 1)\phi'\phi'' + 2\phi\phi'(\phi^{2} - 1) = 0$$
(13)

$$(v^{2} - 1)\phi^{\prime 2}\frac{1}{2} + \frac{1}{2}(\phi^{2} - 1)^{2} + C = 0$$
(14)

Using boundary conditions

$$\phi(\pm\infty) = \pm 1, \ \phi'(\infty) = 0 \Rightarrow C = 0 \tag{15}$$

$$(v^2 - 1)\phi'^2 + (\phi^2 - 1)^2 = 0$$
(16)

$$(1 - v^2)\phi'^2 = (\phi^2 - 1)^2 \tag{17}$$

$$\phi' = \pm \frac{(\phi^2 - 1)}{\sqrt{(1 - v^2)}} \tag{18}$$

$$\phi = th\left(\mp \frac{(x - x_0) - v(t - t_0)}{\sqrt{(1 - v^2)}}\right)$$
(19)

For numerically solution we use 4 order Runge-Kutta method





ϕ^6 model.

There the potential is

$$U = \frac{1}{2}\phi^2 (1 - \phi^2)^2 \tag{20}$$

and vacua give following boundaries

$$\phi(-\infty) = 0, \quad \phi(+\infty) = 1 \tag{21}$$

$$\phi(-\infty) = -1, \ \phi(+\infty) = 0$$
 (22)

analitical solution is

$$\phi = \pm \frac{1}{\sqrt{1 + e^{\pm 2(x - x_0)}}} \tag{23}$$





5 Sine-Gordon model

$$U = 1 - \cos(\phi)$$

$$\phi(-\infty) = 0, \ \phi(+\infty) = 2\pi$$

numerically solution is



6 Parametrisesd model

$$U = (1 - \epsilon)(1 - \cos(\phi)) + \frac{\epsilon \phi^2}{8\pi^2}(\phi - 2\pi)^2$$

$$\phi(-\infty) = -1, \ \phi(+\infty) = 1$$

potentials, correspondings different ϵ







solutions for different potentials





7 References

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- W. H. Press, S. A. Teukolsky, W. T. Vetterling, and B. P. Flannery. Numerical recipes 3rd edition: The art of scientific computing. Cambridge university press, 2007